

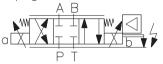
# PROPORTIONAL DIRECTIONAL CONTROL VALVES

|KE 6008 | 07/14 |

Dn 06 | pmax 35 MPa | Qmax 40dm³/min

Proportional directional control valves QSE4-06 with inductive spool position sensor are used to control flow of fluid in hydraulic circuit in both directions.

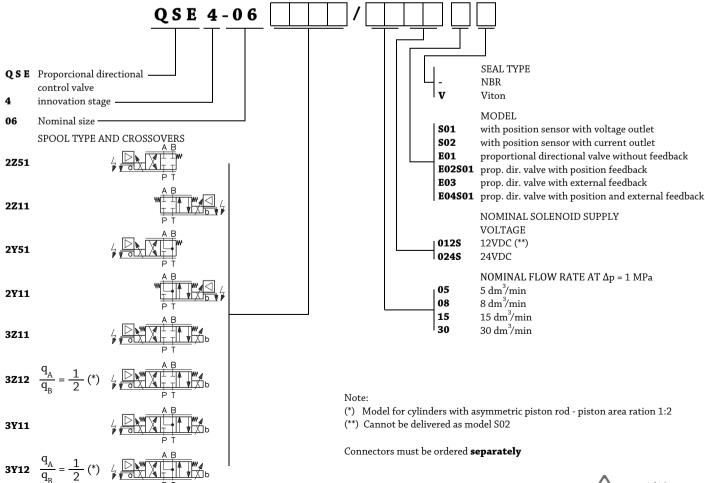
Dn 06, NG 06  $\mid$  Installation dimensions according to DIN 24 340, ISO 4401, CETOP 3  $\mid$  Compact design  $\mid$  High sensitivity  $\mid$  tiny hysteresis  $\mid$  Digital control



### **DESCRIPTION**

Proportional directional control valves QSE4-06 with inductive spool position sensor are used to control flow of fluid in hydraulic circuit in both directions and comprises of cast iron housing, special control spool, two centering springs with supporting washers, one or two proportional solenoids, position sensor and (according to the desired version) a box with digital control unit. In the version without the control unit the solenoids and the position sensor are connected through EN 175301-803 and G4W1F connector plug respectively. In the version with the integrated control unit is the valve equipped with electronic control box that can be (together with position sensor) mounted on both solenoids. The connection between the sensor and the control unit is provided by a cable. In the two solenoids version, the solenoid mounted on the opposite side of the electronic control box is connected through EN 175301-803 connector. The supply voltage, control signal, position sensor check output (if available) and output voltage +10VDC is connected through 7-pin connector M23. The valve housing is phosphate coated, solenoids and position sensor are zinc coated.

### **ORDERING CODE**





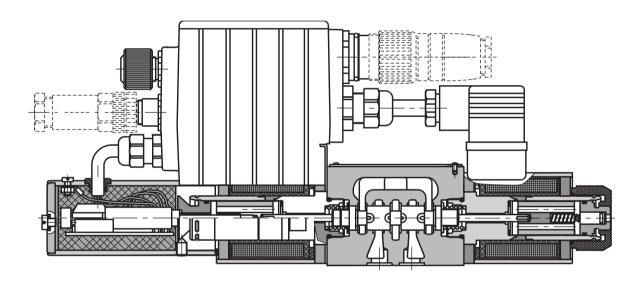
#### **ELEKTRONICS**

Measuring system of the position control consist of a differential transformer with core and the evaluating electronic unit. External feedback can be connected using 5-pin connector M12x1 that also provides supply voltage ( $\pm$ 24VDC |  $\pm$ 12VDC |  $\pm$ 5VDC) for external sensor.

Digital control unit allows the proportional valve to be controlled on the basis of the data acquired from two feedback circuits. The protportional valve can be used as follows:

- 1) Proportional directional valve (no feedback) E01,
- 2) With the internal feedback from the spool position sensor E02S01,
- 3) With the external feedback (pressure sensor, pocition sensor, etc.) E03,
- 4) With the internal and external feedback E04S01.

Solenoid control current is controlled using PWM. Control unit is equipped with an internal current feedback, Controll current can (in case of need) be modulated by signal of dynamic lubrication. Particular function parameters can be software set using RS232 interface. Green and red LED indicate propper and impropper function respectively. Valve factory settings depends on the ordered version. Please note that the version of the valve with the external feedback is recommended to be consulted with the manufacturer.



### INSTALLATION, SERVICE AND MAINTENANCE

Proportional directional control valves QSE4-06 are designed for panel installation. They are being mounted by four screws M5x45 DIN 912-10.9 with torque 8.9Nm. The reliability of the valves is conditional upon use of prescribed working fluid, especially its parameters such as cleanness and temperature. It is required that the contact surfaces of the valve and the subplate must be clear and intact before installation. O-rings must not be disshaped or demaged by any means. Flatness deviation and roughness of the subplate shall not exceed 0.01/100 mm and Ra = 1.6  $\mu$ m respectively. Proportional directional valves can be installed in any position and do not require any special maintenance.

### **DELIVERY**

Directional control valves QSE4-06 are delivered assembled including O-rings and solenoids with connector plugs. Spare parts and mounting screws are not included in the package. These must be ordered separately.



# **TECHNICAL DATA**

Technical data	Symbol	Unit	Value		
Nominal size	Dn	mm	6		
Max. operating pressure in ports P, A, B	рмах	Mpa	35		
Max. operating pressure in port T	рмах,т	MPa	21		
Hydraulic fluid	Hydraulic	oils of power classes (HL, H	LP) according to DIN 51524		
Fluid temperature range NBR (Viton)	t <sub>PO</sub>	°C	-30+80 (-20+80)		
Max. ambient temperature	t <sub>A</sub>	°C	+50		
Viscosity range	$\nu$ mm <sup>2</sup> /s		20 400		
Maximum degree of fluid contamination	Class 21/18/15 accordi	ng to ISO 4406 (1999)			
Nominal flow at $\Delta p = 1$ MPa	Q	dm <sup>3</sup> /min	15 / 30		
Hysteresis - open loop	H <sub>O</sub> %		< 6		
Hysteresis - closed loop (position)	H <sub>C</sub>	%	< 0.5		
Weight - QSE4-062	m	lra .	2.3		
- QSE4-062	III	kg	2.8		
Mounting position			optional		
Enclousure type according to EN 60 529			IP65		

# TECHNICAL DATA OF POSITION SENSOR - VOLTAGE OUTLET

Technical data	Symbol	Unit	Value					
Operating pressure	p	Мра	max. 35, static					
Electric connection	Electrical connector G4V	V1F Hirschmann (*)						
	1 - power supply							
Contact assignment	2 - output signal							
Contact assignment	3 - ground GND	3 - ground GND						
	4 - not used							
Enclosure according to EN 60 529			IP65					
Measured distance	1	mm	8					
Operating voltage	U	V (DC)	9.6 - 30					
Linearity error		%	<1					
Output voltage	$U_{OUT}$	V (DC)	0 - 5					
Output signal range								
- position 0			2,5					
- 1 solenoid (stroke 2.8mm)	$U_{OUT}$	V (DC)	0.75 - 2.5					
- 2 solenoids (stroke ±2.8mm)			0.75 - 4.025					
Max. load current	$I_{MAX}$	mA	2					
Output signal ripple								
- at load current 0 mA		$\mathrm{mV}_{\mathrm{p-p}}$	<20					
- at load current 2 mA		111 v p-p	<15					
Additional signal error at								
- Temperature change between 080°C	typical <0.2% / 10K, ma	x 0.5% / 10K						
- Between 025°C	max 0.5% / 10K							
- Load current change from 0 to 2 mA	0.1%							
Input voltage change								
- from 9,6 to 14,4 V	$\Delta U_{OUT}$	%	<0.1					
- from 14,4 to 30 V	70001	,,	<0.25					
long-term drift (drift/30days)		%	<0.25					
Cut-off frequency								
- 3dB amplitude fall	f	Hz	>600					
- frequency (phase 90°)	1	112	>600					



# **TECHNICAL DATA OF POSITION SENSOR - CURRENT OUTLET**

Technical data	Symbol	Unit	Value				
Linearity		%	<1				
Operating pressure	p	MPa	max. 35, static				
Electrical connection	Electrical connector G4V	W1F Hirschmann (*)					
	1 - power supply	1 - power supply					
Contact assignment	2 - output signal						
Contact assignment	3 - ground (GND)						
	4 - not used	4 - not used					
Enclosure type according to EN 60 529			IP65				
Operating voltage	U <sub>cc</sub>	V (DC)	20 - 30				
Load current	$I_{\mathrm{Z}}$	mA	<35				
Output signal range		mA	4 - 20				
Output signal range							
- position 0			12				
- 1 solenoid (stroke 2.8mm)	$I_{OUT}$	mA (DC)	6,6 - 12				
- 2 solenoids (stroke ±2.8mm)			6,6 - 17				
Additional output signal error at							
- Temperature change from +1055°C			0,2% / 10K				
- 50% impedance change			<0,1% / 10K				
- Input voltage change in the range of operating	voltage		<0,05%				
Load impedance	$R_{\rm Z}$		<500				
Output signal ripple		mA RMS	<0,02				
Cut-off frequency - 3dB amplitude fall	f	Hz	>800				

<sup>(\*)</sup> Only for S01 and S02 model

# **TECHNICAL DATA OF SOLENOIDS**

Technical data	Symbol	Unit	Value
Coil nominal voltage	Us	V (DC)	12   24
Limiting current	$I_{S-MAX}$	A	2,4   1,0
Resisitance at 20°C	R <sub>S20</sub>	Ω	2,3   13,4

# TECHNICAL DATA OF ELECTRONIC

Technical data	Symbol	Unit	Value			
Supply voltage with polarity inversion protection	Us	V (DC)	11,2 - 28 (residual ripple <10%)			
Input: setpoint / control signal	±10V,	±10V, 0 - 10V, ±10mA, 4 - 20mA, 0 - 20mA, 12mA ± 8mA				
Input: spool position sensor signal		0 - 5 V				
Input external feedback signal		0 - 10V, 4 - 20mA,	0 - 20mA			
A/D resolution	12bits					
Output: solenoids	2 PWM outputs (max 3.5 A)					
PWM frequency	$f_{PWM}$	Hz	18000			
Parameter adjustment period	$T_R$	μs	170			
EMC interference resistance	61000 - 6 - 2 : 2005					
EMC radiation resistance	55011 : 1998 class A					
Parameter settings	Serial port RS 232 (zero n	nodem), 19200 Bauds 8 da	ta bits, 1 stopbit, no parity, Special SW			

# **ACCESSORIES**

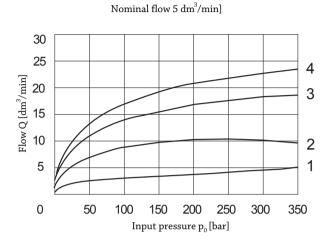
1	Connecting cable to PC (2m), CD with SW and manual
2	Connecting cable to PC (5m), CD with SW and manual
3	Connecting cable to PC (2m)
4	Connecting cable to PC (1m)



### **OPERATING LIMITS**

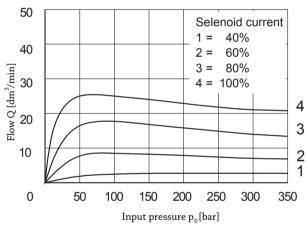
Only for E01 version

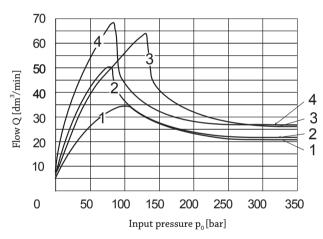
 $P \rightarrow A / B \rightarrow T \text{ nebo } P \rightarrow B / A \rightarrow T$ 



30 25 Flow Q [dm<sup>3</sup>/min] 15 10 4 3 2 5 1 0 50 100 150 200 250 300 350 Input pressure  $p_0$  [bar]

Nominal flow 8 dm<sup>3</sup>/min]

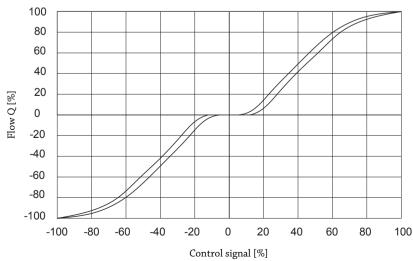




Note: Measured at  $v = 32 \text{ mm}^2/\text{s}$ 

# FLOW CHARACTERISTICS

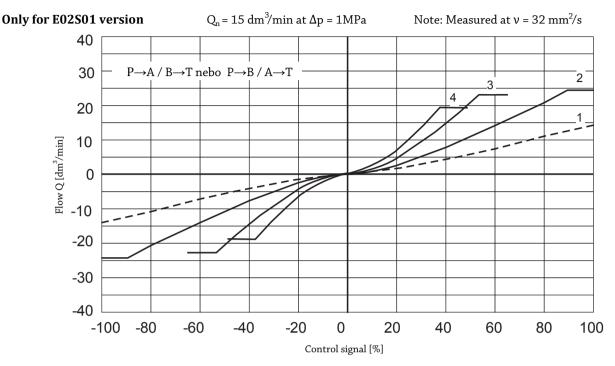
Only for E01 version



Note: Measured at input pressure  $\Delta p = 1$  MPa, v = 32 mm<sup>2</sup>/s



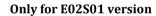
### FLOW CHARACTERISTICS



1	∆p <sub>n</sub> =	10 bar
2	Δp =	50 bar
3	Δp =	160 bar
4	Δp =	320 bar

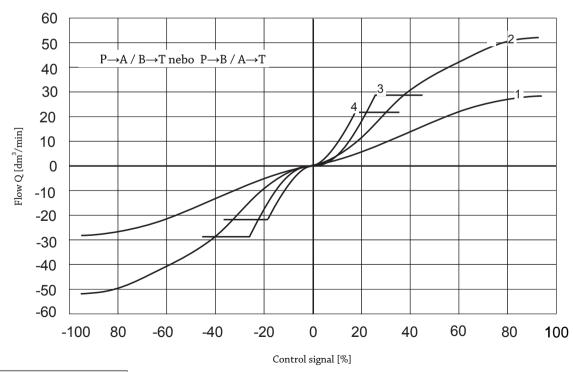
 $\Delta p~$  - differential valve pressure (inlet pressure  $p_{_{V}}$  minus load pressure  $\Delta p$  and return pressure  $p_{_{\rm T}}$ 

 $\Delta p_{\rm n}\text{-}$  differential valve pressure at nominal flow  $Q_{\rm n}$ 



 $Q_n = 30 \text{ dm}^3/\text{min at } \Delta p = 1\text{MPa}$ 

Note: Measured at  $v = 32 \text{ mm}^2/\text{s}$ 



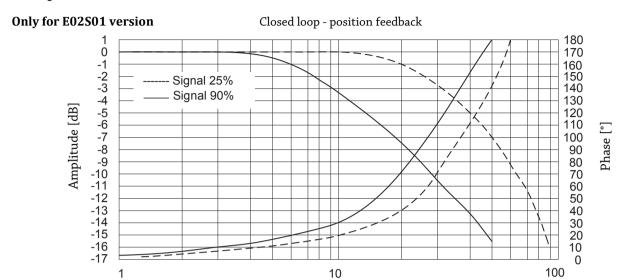
1	Δp <sub>n</sub> =	10 bar
2	Δp =	50 bar
3	Δp =	160 bar
4	Δp =	320 bar

 $\Delta p~$  - differential valve pressure (inlet pressure p~ minus load pressure  $\Delta p~$  and return pressure  $p_{_{\rm T}})$ 

 $\Delta p_{\rm n}\text{-}$  differential valve pressure at nominal flow  $Q_{\rm n}$ 

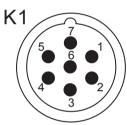


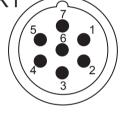
# **FREQUENCY RESPONSE**



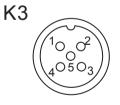
Frequency [Hz]

# **CONNECTORS**







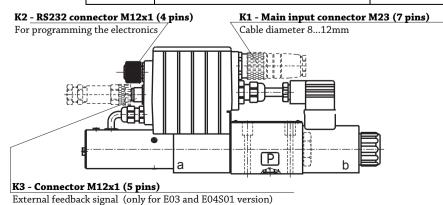


onnector K1 - M23					
Technical data	Value				
* Power supply input	11.2 28V DC				
* Ground (GND - power supply)	ov				
Control signal	according to the configuration				
Ground (signal)	ov				
Power reference signal	+10VDC/max. 10mA				
Control signal of spool position sensor	05V				
*Protective earth (PE)					
	* Power supply input  * Ground (GND - power supply)  Control signal  Ground (signal)  Power reference signal  Control signal of spool position sensor				

\*Recommended min. lead cross section 0.75mm<sup>2</sup>

Connector	Connector K2 - M12x1 (male)					
PIN	Technical data	Value				
1	TxD	according to the				
2	RxD	RS 232 standard				
3	Ground (signal)	OV				
4	Not used					

nnector K3- M12x1 (female)				
PIN	Technical data	Value		
1	Power supply (output)	11.2 28VDC/max.		
2	External feedback signal	dle nastavení		
3	Ground	0V		
4	Not used			
5	Not used			

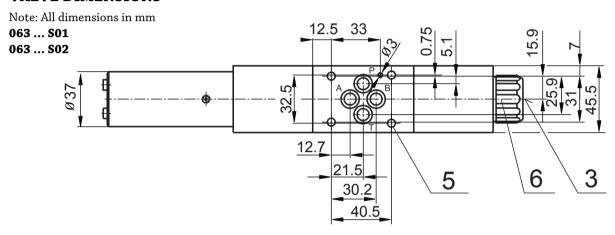


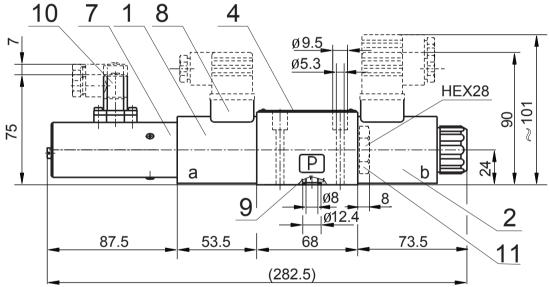


### **VALVE FACTORY SETTINGS**

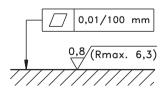
		Model							
Signal	E	E01 E02S01		E03		E04S01			
	1 solenoid	2 solenoids							
Control signal	010V	± 10V							
External feedback signal	-	-	-	-	010V				
Spool position sensor signal	-	-	0	.5V	- 05V		.5V		

### **VALVE DIMENSIONS**





- 1 Solenoid a
- 2 Solenoid b
- 3 Manual override
- 4 Type and version plate
- 5 4 Mounting holes
- 6 Solenoid fixing nut
- 7 Spool position sensor
- 8 Solenoid supply connector
- 9 Square ring  $9.25 \times 1.68$  (4pcs) supplied in the package
- 10 Position sensor connectors
- 11 Plug screw only for the valve with one solenoid, HEX 28, spool 2Z51 a 2Z11



Required surface finish of the interface



### VALVE DIMENSIONS

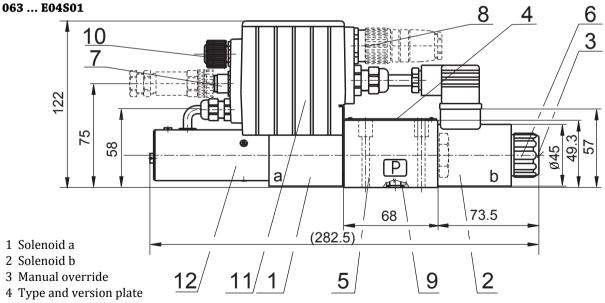
Pozn: All dimensions in mm

## 063 ... E01 - without connector plug for spool position feedback

063 ... E03 max. 70 max. 147 8 4 HEX28 86 8 75 P b а 8 68 74.5 1 Solenoid a 2 Solenoid b (216) 3 Manual override 4 Type and version plate 5 12 2 9

- 5 4 mounting holes6 Solenoid fixing nut
- 7 Connector M12x1 for connection of external feedback
- 8 Main supply connector M23
- 9 Square rings 9.25 x 1.68 (4pcs) supplied in the package
- 10 Connector cover M12x1 for programming
- 11 Plastic box with integrated electronics
- 12 Plug screw only for the valves with one solenoid, HEX 28 spool 2Z51 and 2Z11

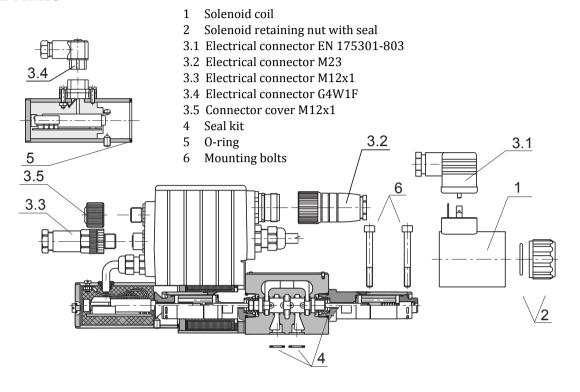
### 063 ... E02S01 - without connector plug for spool position feedback



- 5 4 mounting holes
- 6 Solenoid fixing nut
- 7 Connector M12x1 for connection of external feedback
- 8 Main supply connector M23
- 9 Square rings  $9.25 \times 1.68$  (4pcs) supplied in the package
- 10 Connector cover M12x1 for programming
- 11 Plastic box with integrated electronics
- 12 Spool position sensor



# **SPARE PARTS**



1. Solenoid coil			
2. Solenoid retaining nut with seal		Standard nut, seal ring 22 x 2	
3.1. Electrical connector EN 175301-803 (selenoid A: grey)		Without rectifier M16x1.5 (bushing bore Ø4-6mm)	
3.1. Electrical connector EN 175301-803 (selenoid B: black)		Without rectifier M16x1.5 (bushing bore Ø4-6mm)	
3.2. Electrical connector M23		7 pins (female)	
3.3. Electrical connector M12x1		5 pins (male), only for E03 and E04S01 version	
3.4. Electrical connector G4W1F			
3.5. Connector cover M12x1			
4. Seal kit	Туре	Dimensions (number)	
		Square ring	O-ring
	Standard NBR70	9.25 x 1.68 (4pcs)	17 x 1.8 (2pcs)
	Viton	9.25 x 1.78 (4pcs)	17.17 x 1.78 (2pcs)
5. O-rings		Standard NBR70, 32 x 2 (2ks)	
6. Mounting bolts (sada)		Dimensions (number)	Tightening torque [Nm]
		M5 x 45 DIN 912-10.9 (4pcs)	8.9

### **NOTES**

Consultancy service is provided by: **PQS Technology, Ltd.** 

Sales department: tel.: +420 313 526 236 Technical support: tel.: +420 313 526 378

Technical support: tel.: +420 313 526 Fax: +420 313 513 091

www.pqstechnology.co.uk



e-mail: export@pqstechnology.co.uk

e-mail: info@pqstechnology.co.uk